ISSN: 2302-9285, DOI: 10.11591/eei.v9i2.1653

An effective transmit packet coding with trust-based relay nodes in VANETs

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Article Info

Article history:

Received Jun 8, 2019 Revised Jun 19, 2020 Accepted Feb 6, 2020

Keywords:

Network coding Optimization Relay node selection Trust calculation VANET

ABSTRACT

Vehicular ad-hoc networks (VANETs) are characterized by limited network resources such as limited bandwidth and battery capacity. Hence, it is necessary that unnecessary use of network resources (such as unnecessary packet transfers) is reduced in such networks so that the available power can be conserved for efficient multicast communications. In this paper, we have presented a transmit packet coding (TPC) network coding in VANET to ensure reliable and efficient multicasting. With network coding, the number of transmitted packets over the network can be reduced, ensuring efficient utilization of network devices and resources. Here, the trust-based graph optimization is performed using Cuckoo search algorithm to select the secure relay nodes. The experimental results showed the superiority of the presented approach compared to the existing techniques in terms of throughput, latency, hop delay, packet delivery ratio, network decoder outage probability, and block error rate.

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1. INTRODUCTION

In recent years, researchers have imagined that data communication can be made progressive and proficient. We send information as packets, which are mixed in a totally arbitrary manner toward one end, and descrambled at the opposite end in a communication network, rather than sending plain information. Network coding was acquainted with the idea to upgrade the throughput of the systems; however, at this point, it is utilized to expand the capability, robustness, tomography, and security of systems [1, 2]. Network coding is characterized as applying codes at nodes in a system. It is a technique for sending messages over the network and for restoring lost information [3]. Network coding in a network is used to encode data acquired from the input links. It has been being used in various executions of information interchange networks, like the Internet, peer-to-peer networks, wireless sensor networks (WSNs), shared systems, cognitive radio networks (CRNs), multicast systems, VANETs, and other rising networks [4].

As of late, VANETs have picked up great fame among industry and scholarly research networks. VANETs use vehicles as versatile hubs in an ad-hoc manner. Each contributing vehicle acts as a remote switch or hub to interconnect with one another. The fixed street side units like traffic light towers set up

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a backbone system to provide network, and in time conveyance, dependable and reliable security-related data. The VANETs standards and executions help in developing quantities of remote items that would now be able to be utilized in vehicles [5-7]. VANET is an ad-hoc mobile system that uses vehicles on the streets as network devices as they form a distributed communication network for message exchanges. A wide scope of utilization can be beneficial for such innovation. Safety applications are road-side security measures that are in place to ensure the safety of road users [8-10].

VANETs are perfect to keep up a high class of administration in strong technological topologies, giving quick steering and security. These challenges affect the testing and utilization of new systems (such as network coding (NC) and cooperative correspondences) to enhance the quality of overall communication experience [11-13]. For this situation, we can accomplish better data transmission use, lessen the system crashes, and diminish the quantity of rebroadcasting occasions by utilizing strategies, for example, the network coding. It is a realized strategy to effectively use data transmission by abusing the communication idea of the remote medium. Network coding diminishes the number of retransmissions by enabling the relay nodes to advance the data pack and to do a type of logic task on them [14-16].

Numerous researchers have proposed distinct network coding methods in VANETs to improve multi-hop routing procedures. In [17-19], a protocol is proposed which uses powerfully produced back-bone vehicles to disperse data pack in the network. Moreover, they utilized network coding to improve data pack gathering likelihood. Another protocol utilizes intra flow and inter-flow coding [18, 19] to decrease the protocol overhead when contrasted with existing protocols. In [20-22] a robust and fast forwarding (ROFF) protocol was proposed for the reduction of excess retransmissions in the system. In [23-25], a multi-hop communication protocol was presented for time-basic emergency messages (EMs) dispersal. This proposed trinary apportioned black-burst-based communicate protocol (3P3B) applies trinary packing at the system layer and mini-distributed interframe space (DIFS) device at the medium access control (MAC) sublayer. Celimuge et al. [26-28] proposed fuzzy broadcast (FUZZBR), a fuzzy logic based multi-hop communicate protocol which has a low message overhead because of its utilization of just specific transfer hubs for data distribution [29-32]. At the point when a transfer hub neglects to retransmit a data pack, the FUZZBR additionally utilizes a lightweight retransmission mechanism [33-35].

The main contributions of this paper are as follows: 1) adaptive quantum logic gate based (AQLG) network coding is presented in VANET in order to achieve efficient and reliable multicasting; and 2) trust-based graph optimization is performed using Cuckoo search algorithm for the effective selection of trustable relay nodes. The structure of the manuscript is composed as Section 2 surveys the papers regarding the proposed strategy. In sections 3, a brief discussion about the proposed approach is presented; section 4 investigates the exploratory outcomes, and section 5 concludes the paper.

2. RELATED WORK

A cross-layer design for both amplify-and-forward (AF) and decode-and-forward two-way relaying (DF-TWR) was proposed by Yanping et al. [21] based on the NC method for the enhancement of the achievable throughput under explicit quality of service (QoS) requirements, such as the most reasonable error rate and delay. They naturally amalgamate adaptive analog network coding (ANC) and network coded modulation (NCM) with truncated automatic repeat request (ARQ) worked at the distinctive OSI layers. Several improved NC-based ARQ procedures were intended at the data-link layer based on the Stop-and-Wait and the Selective Repeat ARQ techniques. However, adaptive ANC/NCM was summoned at the physical layer based on the estimated packet error ratio (PER). They built up a novel transmission procedure for choosing the ideal group sizes for the relay to the destination connections which must be adjusted to both pair of channel conditions.

A cross-layer analysis structure and execution assessments of cooperative ARQ with opportunistic multi-point relaying (OMPR) in versatile systems were proposed by Hsin-Li & Sau-Hsuan [22]. This proposal considered 3 exemplar OMPR functions and their combinations for opportunistic distributed space-time coded (ODSTC) retransmissions in time-division duplex LTE-A frameworks. As evidenced by the coordination delays of the OMPR functions, it is possible to adequately assess the influence of channel blurring on the spatial and temporal varieties associated with ODSTC-based ARQ, as well as their effects on the transmission energy consumption, framework throughput, and relays queuing delays under the system. According to the analytical outcomes, a rating technique was additionally proposed to augment the framework throughput subject to requirements on packet error rates at mobile stations (MSs) and queuing delays at relay stations (RSs).

Arghyadip & Rajarshi [23] proposed consistent communication in a real-life topology, where connection misfortune probabilities were unique in relation to one another. They determined the closed-form expressions and examined asymptotic conducts for the expected number of transmissions using stop-and-hold

up ARQ and NC as error control components. In the physical layer cooperative broadcast, numerous hubs can transmit all things considered to exploit spatial variety. They integrate the possibility of physical layer cooperative communication with ARQ and NC independently, to acquire further unwavering quality. The numerical outcomes based on their asymptotic examination showed that NC offers more consistency than stop-and-hold up ARQ. In any case, as the size of the participating set increases, both plans offer similar dependability.

Lingzhi Li et al. [24] proposed a network coding with crowdsourcing-based trajectory estimation (NC/CTE) method for data transmission in VANET. Key points were pre-designated in the movement area. At a different time, every node estimates the key points discovered by the other nodes in the explored area using a crowdsourcing method that depends on GPS pre-trajectory navigation. NC, recoding and reverse forwarding are employed for data propagation based on the outcome of the trajectory estimation by the nodes.

Angelos et al. [25] proposed a cross-layer systematic model for the investigation of network coding based ARQ medium access control (MAC) protocols in correlated moderate blurred conditions, where two end hubs are supported by a group of relays to trade information packages. Angelos et al. [25] presented an NC-based MAC protocol for VANETs which depends on the cooperative ARQ techniques. This protocol controls channel access between a set of relays and can use NC to reduce the total number of transmissions, thus improving the networks' performance in terms of QoS metrics.

The existing works have shown that link interruption can occur due to issues like the inter-vehicular mobility links, excessive inter-vehicular spacing, and message transmission failures. Being that only one relay is involved in the communication, the effects of the collision and idles lots on the network's performance can be ignored. Moreover, increased energy consumption, and decreased transmission security are the problems [21-25] in the existing works. The existing works contributions and their benefits and limitations are given in Table 1.

Table 1. The existing works

Author	Main contribution	Benefits	Limitations
Yanping et al. [21]	Truncated-ARQ	Bidirectional network coding scenarios. Higher Throughput	 Need to extend the physical layer techniques. Improvement is needed in Latency
Hsin-Li & Sau-Hsuan [22]	ARQ with OMPR in mobile networks.	Provides fewer energy consumptionsProvides nearbest system throughput.	 Delay is not reduced.
Arghyadip Roy and Rajarshi Roy [23]	NC over stop-and-wait ARQ in a practical access point model.	 Proposed network coding offers more reliability 	 Go-back-N and selective repeat ARQ with NC.
Lingzhi Li et al. [24]	NC/CTE	It improves the reliability and scalability of vehicular networks.	 Need to change the coding steps in NC/CTE for less overhead ratio in the future.
Angelos Antonopoulos et al. [25]	NC-based ARQ MAC protocols	 Energy efficiency, high throughput, and highlighting the importance of cross-layer approaches. 	 Low enhancement of the current NC-based MAC protocols in terms of performance.

The objectives of this work are: i) to give general physical (PHY) layer theoretic expressions for assessing vital system parameters, pertinent in two-way broadcast, ii) to show how these expressions are combined in hypothetical models of the upper layers (i.e., MAC), and iii) to examine the execution of newly proposed NC- assisted cooperative ARQ (NCCARQ) MAC procedure under interrelated shadowing conditions.

3. PROPOSED METHODOLOGY

TPC-MAC was developed for the arrangement of the transmissions between a set of relay nodes in a bidirectional manner between 2 hubs in vehicular networks. Principally, TPC-MAC was developed to empower the versatile stations in requesting for connectivity via a set of trusted nodes upon receiving an incorrect information package. Secondly, the proposed protocol was developed to enable the relay nodes to execute NC on packets before their transmission. Figure 1 represents a simple scenario of the basic concept of the proposed TPC-MAC. The scenario in Figure 1 considered wireless communication between

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a base station (S) and a mobile destination (D). In this situation, many packets will be errone ously received since the destination vehicle is moving along the boundaries of the source's range. However, vehicles moving within the transmission range (between source and destination) constitute potential relays due to the high chance of correctly receiving the propagated data.

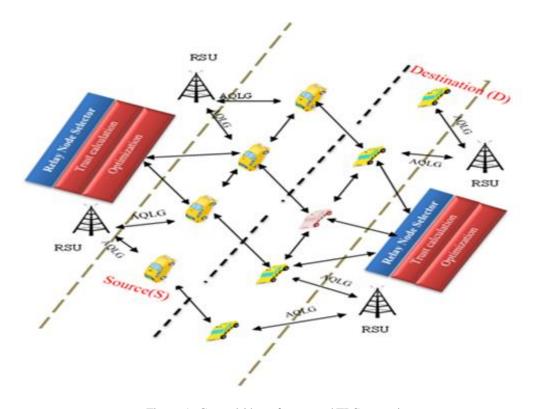


Figure 1. General idea of proposed TPC operation

The VANET comprises a set of nodes $\bar{N} = \{n_1, n_2, n_3, \dots, n_k\}$ and assumes the source as n_1 and the destination as n_k . In the proposed work, data is transferred from the source to the destination nodes through the relay nodes. To avoid failures in data transmission, the reliable relay nodes are selected by utilizing trust-based graph optimization. The trust graph optimization is performed by utilizing the Cuckoo search algorithm adapted to the topology of the cooperation cluster relay nodes selection. The detailed explanation of the proposed design process is discussed in the subsequent sections.

3.1. Trust calculation for relay nodes

Trust is the level of consistency about the data. Trust can similarly be portrayed as the confidence level of a specific node to complete allotted work within some time. The trust of hubs is calculated by the condition (1).

$$T_n = \frac{\sum_{i=1}^n D_i * \tau}{\sum_{i=1}^n D_i}$$
 (1)

where, T_r is the trust of the node, τ is the level of discrete trust, D_i is determined by the condition (2);

$$D_i = \Pi(1 - \alpha_t) \tag{2}$$

where T_k is the trust of every task of node and α_t is determined by the condition (3);

$$\alpha_t = \frac{1}{1+t} \tag{3}$$

Here, t is the task processing time of a specific node. At that time, the cuckoo search optimization algorithm selecting the relay nodes viably dependent on the determined trust esteems.

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3.2. The behavior of the relay selection

As per [26], the relay ensures the maintenance of a queuing buffer in a bid to keep the data received from the slower source; meanwhile, if the source is sending data in the same rate, the relay is chosen randomly. In our proposed technique, the optimized relay is selected using Cuckoo search algorithm recently presented by Yang and Deb. To apply this as an optimization tool, Yang and Deb utilized three ideal rules:

- a. Every cuckoo lay one egg, which signifies a set of solution coordinates, at a time and dumps it in an arbitrary nest;
- b. A portion of the nests comprising the best eggs, or solutions, will extend to the next subsequent generation;
- c. The quantity of nests is fixed and there is a likelihood that a host can find an outsider egg. If this occurs, the host can either dispose of the egg or the nest and this outcome in creating another nest in a new location.

Based on these idealized rules, the basic steps of the CS can be summarized as shown in the pseudocode presented in Algorithm 1.

Algorithm 1: Pseudocode of the Cuckoo Search (CS)

```
Begin
        Objective function f(z), z = (z_1, z_2, .....z_d)^T
        Generate initial population of
        n' Host nests z_i (i = 1, 2, 3 ... n')
        While (t' < Max generation) or (stop criterion)
                Get a cuckoo randomly by Levy flights
                Evaluate its fitness \widetilde{F}_i
                Choose a nest among n'(say, j)randomly
                \mathbf{If}(\widetilde{F}_i > \widetilde{F}_i),
                         Replace j by the new solution;
                End
                A fraction (p_a) of worse nests are
                abandoned and new ones are built;
                Keep the best solutions (or nests with quality
                solutions);
                Rank the solutions and find the current best
        End while
        Post process results and visualization
End
```

For each iteration (t'), a cuckoo egg i, is chosen arbitrarily and different solutions $z^{(t'+1)}$ are produced. This arbitrary search accomplished more effectively by utilizing Levy flights rather than with a straightforward arbitrary walk. The Levy flights are a sort of arbitrary walk in which the steps are characterized in terms of the step-lengths that pursue specific likelihood dissemination in which the directions of the steps must be isotropic and arbitrary. For this situation, the general condition for the Levy flight is specified by,

$$z_i^{(t'+1)} = z_i^{(t')} + \alpha \oplus Levy(\beta)$$
(4)

where the superscript t' is utilized to demonstrate the current generation, the symbol \bigoplus is utilized to designate the entry-wise multiplication and $\alpha > 0$ represents the step size. This step size decides how far a particle can move by arbitrary walk for a fixed number of cycles. The transition probability of the Levy flights in condition (5) is modulated by the Levy dissemination as:

$$Levy(\beta) \sim g^{-\beta}, (1 < \beta \le 3) \tag{5}$$

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The condition (5) has an infinite change with an infinite mean. From the execution viewpoint, primarily, a random direction regarding to uniform distribution is preferred; then, the sequence of steps succeeding the selected Levy distribution is produced. The cuckoo search optimization algorithm assesses the fitness of the new solution and relates it with the present one. At that point, the current solutions are ordered at every iteration step dependent of their fitness and the finest solution is reached so far is kept as the vector (z'_{best}) . The algorithm is applied iteratively until a prescribed stopping criterion is met.

Node Insertion

For node insertion $z_{best}^{'}$ esteems are considered which the trust results of every node in VANET. Each node is then categorized according to their trust values. At last, the secure nodes are chosen as relay nodes dependent on the trust values for the esteems for the information transmission.

Link insertion

These chosen nodes are then connected to other nodes which are not a part of source and destination. The node which holds the higher trust esteem is chosen as reliable nodes for the information transmission. By means of the reliable nodes data is transmitted from the source to the destination without failures.

3.3. Transmit packet coding

The proposed work in this study aims at achieving a better bandwidth utilization, as well as minimize network congestion during multimedia data transmission. Therefore, the NC technique was used to minimize the number of data retransmissions. Our proposed work environment is similar to the given Figure 1, where, the source is positioned at the opposite terminals of the same road, sharing N hop's area of interest. The non-safety data are disseminated by the source to the vehicles in the shared road section between them.

Here, instead of having the relay broadcasting, our proposed work utilizes the trust-based optimized relay selection for the data transmission and encoding into one packet prior to their rebroadcasting in the network. This minimizes the bandwidth utilization and delays at the relay. It is assumed that the relay can forward the packets and execute AQLG operation on the transmitted packets prior to their rebroadcasting. It is also believed that the relay is aware of the average data rates sent by the source.

3.3.1. TPC operational example

Simple network topology with four stations is considered, every one of them in the transmission range of one another. A source node (n_1) transmits a data packet (A') to a destination node (n_k) that does likewise have a packet (B') intended to the source station. Besides, there are two helper or relay nodes $(\bar{H}_1$ and $\bar{H}_2)$ that support this specific bidirectional communication. The complete process is described as pursues,

Instant 1: At instant t'_1 , source node n_1 transmits the data packet A' to destination node n_2 .

Instant 2: Upon reception, at instant t_2' , destination node n_2 neglects to demodulate the information packet, therefore broadcasting a packet request (PR) packet requesting for the cooperation of the neighboring relay nodes along with the data packet B', destined to the source node n_1 .

Instant 3: The acceptance of PR at instant t_3' activates the nodes \bar{H}_1 and \bar{H}_2 to become activated relays and check the trust based optimized set up their link to participate in the dispute contention phase.

Instant 4: At instant t'_4 , the setup link of \bar{H}_1 terminates and \bar{H}_1 transfers the coded packet A'B' to the nodes n_1 and n_k concurrently.

Instant 5: At instant t_5' , the destination node n_k retrieves the original packet A' and sends back an acknowledgment (ACK) packet subsequently it can decipher legitimately the Adaptive quantum logic based coded packet.

Instant 6: At instant t'_6 , the source node n_1 acknowledges the packet B' since it can decode appropriately the coded packet A'B'. The network topology operation with transmit packet coding is depicted in Figure 2.

The proposed AQLG-MAC protocol is intended to organize the transmissions among a group of relays that encourages a bidirectional inter-nodal communication in VANET. The first necessity of AQLG-MAC is that all nodes in the system ought to work in indiscriminate so as to have the ability to tune in to all on-going transmissions and cooperate whenever required. The second fundamental necessity of AQLG-MAC is that a duplicate of all the received packet must be stored by the nodes until an acknowledgment is received from the destination station. The stations that receive the *PR* packet becomes the potential candidates that will serve as the active relays for communication. Accordingly, the formation

of the relay set is initiated after gathering the *PR*, while the participant's stations prepare to propagate their information. Being that the packets designated to the destination and source have been stored by the partners, they utilize the transmit packet coding technique to produce a new coded packet. Consequently, the active relays strive to access the channel in a bid to transmit the TPC packet.

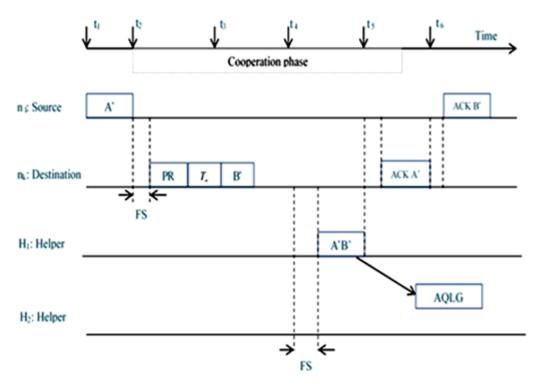


Figure 2. Network topology operation with a frame sequence

3.3.2. Adaptive quantum logic coding

Quantum coding is a state which is not equal to straightforwardly produce of subsystems; this is additionally clarified mathematically. For example, there are two relay nodes R_A R_B and the corresponding composited framework R_{AB} . The quantum conditions of subsystems as well as composited system are $|\psi_A\rangle$, $|\psi_B\rangle$ and $|\psi_A\rangle \otimes |\psi_B\rangle$ correspondingly. If two subsystems entangled each other, the relationship can be described as pursues,

$$R_{AB} = R_A \otimes R_B \tag{6}$$

Nevertheless,

$$|\psi_{AB}\rangle \neq |\psi_{A}\rangle \otimes |\psi_{B}\rangle \tag{7}$$

There is a composited quantum bit $|\psi_{AB}^{+}\rangle$, which is quantum entangled state, furthermore, $|\psi_{A}\rangle$ and $|\psi_{B}\rangle$ is entangled pair. It must fulfill the beneath condition,

$$|\psi_{AB}^{+}\rangle = \frac{1}{\sqrt{2}}\{|0_{A}\rangle \otimes |1_{B}\rangle + |1_{A}\rangle \otimes |0_{B}\rangle\} \tag{8}$$

The feature of this condition can be described that when the, $|\psi_A\rangle$ is $|0\rangle$ the state of $|\psi_B\rangle$ certainly is opposite $|1\rangle$ vice versa. However, when $|\psi_A\rangle$ is collapsed to Eigen state $|1\rangle$ by measurement, $|\psi_B\rangle$ unavoidably collapses to opposite Eigen state $|0\rangle$ vice versa. Likewise, the data packet is coded before the transmission to secure the transmission data. Finally, the coded data packet is transmitted through the chosen relay nodes to the destination node securely. The overall flowchart of the proposed technique is given in Figure 3.

Once the network coded packet has been received by the source and the destination from the relay, they can decode the packet and retrieve the respective original data packets. Later, they will acknowledge the receipt of the packet by sending the respective ACK, thereby, ending the cooperation phase. Upon

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receiving the ACK, the relays are informed about the completion of specific communication, so they can delete the packets of their buffers. Should the received coded packets fail to be retrieved after a certain maximum cooperation timeout as a result of transmission errors, the relays will be mandated to re-forward the NC packet.

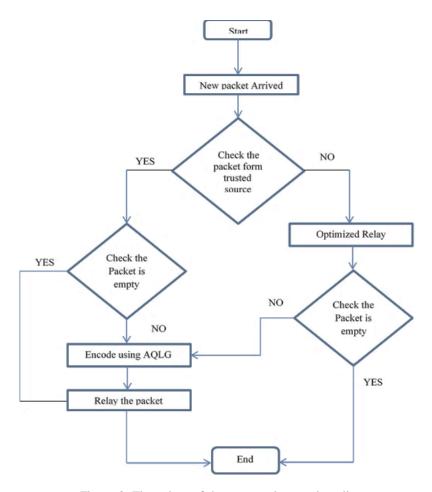


Figure 3. Flow chart of the proposed network coding

4. RESULTS AND DISCUSSION

The implementation of our proposed adaptive quantum logic-based network coding is performed in the working platform of MATLAB. In order to examine the performance of the proposed transmit packet, coding is distinguished with the existing random linear coding (RLC) [27], NCCARQ-MAC [28] protocol and Huffman coding [26] techniques in terms of throughput, hop delay, network decoder outage probability, block error rate, latency, and packet delivery ratio. Table 2 presents the parametric configuration of the network based on the IEEE 802.11 physical layer. The time for NC application to the data packets was considered insignificant since the coding takes place between only two packets.

Table 2. System parameters

	1
Parameter	Value
MAC header	64 bytes
PHY header	96µs
ACK, RFC	14 bytes
DAT A packets	1000 bytes
SIFS	$10\mu s$
DIFS	$20\mu s$

Moreover, this study considered different network scenarios with different SNR values between the source and the destination. The transmission of the control packets was executed at the rate of 6 Mb/s,

while the data packets were transmitted at the rate of 6, 28 and 64 Mb/s for low, medium and high SNR values, respectively. With the positioning of the relays close to the destination, it was assumed that in all the scenarios, the transmission rates are 6 for control packet and 64 Mb/s for the data packets. The 3 unique simulation scenarios are presented in Table 3.

Table 3. Simulation scenarios

SNR(S-D)	Source control rate (Mb/s)	Source data rate (Mb/s)	Relay control rate (Mb/s)	Relay data rate (Mb/s)
Low	6	6	6	64
Medium	6	28	6	64
High	6	64	6	64

The performance of the proposed TPC is compared with the existing random linear coding (RLC), NCCARQ-MAC, and Huffman coding techniques regarding throughput, latency, hop delay, packet delivery ratio (PDR), block error rate (BER), and network decoder outage probability. The comparison results in terms of different performance measures are given in Table 4.

Table 4. Comparison of performance of proposed coding with existing RLC and Huffman coding

Methods	Throughput	Latency	Hop delay	PDR	BER	Outage probability
Proposed AQLG coding	5.42×10^8	1.32 X 10 ⁻⁶	9.72 X 10 ⁻³	92.81	0.10	0.81
Random Linear Coding	4.53×10^{8}	1.45 X 10 ⁻⁶	0.010	90.62	0.15	0.975
Huffman coding	4.09×10^{8}	1.59 X 10 ⁻⁶	0.012	88.42	0.16	0.987
NCCARQ-MAC	3.37×10^{8}	1.52 X 10 ⁻⁶	0.012247	87.22555	0.205701	1

4.1. Throughput

Throughput is the maximum amount of data which can be effectively transmitted within one scheduled time. A systems' total throughput is the sum of the overall throughput created by the direct and effective transmissions of bits plus the throughput determined by the cooperation phase after receiving the erroneous packet. Mathematically, the throughput of a system is represented as:

$$\bar{S}_{total} = \bar{S}_D + \bar{S}_{co-operative} \tag{9}$$

$$\bar{S}_D = (1 - \overline{PER_{S \to D}}) * \frac{\bar{P}_{load}}{\bar{T}_D}$$
(10)

$$\bar{S}_{co-operative} = 2 * \overline{PER_{S \to D}} * \frac{\bar{P}_{load}}{\bar{T}_{total}}$$

$$(11)$$

where $\overline{PER_{S\to D}}$ =rate of packet error between the source and the destination, \bar{P}_{load} a=average packet payload, \bar{T}_D =average time for a single data packet transmission from the source to the destination, and \bar{T}_{total} =total time required to complete a cooperative transmission through relays. The comparison graph of the proposed TPC with the existing random linear coding (RLC), NCCARQ-MAC and Huffman coding in terms of throughput is depicted in Figure 4.

Figure 4 shows that the throughput of the proposed TPC is significantly higher than the existing RLC, NCCARQ-MAC and Huffman coding techniques. The throughput value of the proposed TPC is 5.42x10⁸ (b/s), RLC is 4.53 X 10⁸ (b/s) comparable to the Huffman coding, which achieves 4.09 X 10⁸ (b/s). The NCCARQ-MAC achieves worst throughput value with 3.37 X 10⁸ (b/s). However, Figure 3 shows that the TPC outperformed the existing NCCARQ-MAC, RLC and Huffman coding.

4.2. Hop delay

The total time from the transmission of data to its reception at the destinations is represented mathematically as:

$$\bar{T}_{time} = \bar{T}_D + \bar{T}_{co-operative} \tag{12}$$

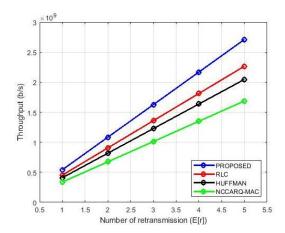
where, \bar{T}_D =average transmission time of one data packet from source to destination, $\bar{T}_{co-operative}$ =average time required to complete a cooperative transmission through relays. The average time spent at the cooperation phase is represented as:

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$$\bar{T}_{co-operative} = \bar{T}_{min-delay} + \bar{T}_{additional} \tag{13}$$

where, $\bar{T}_{min\ -delay}$ =minimum average delay if there should be perfect scheduling among the relay, $\bar{T}_{additional}$ =additional delay due to the contention phase which has been received in our protocol for the probability of collisions to be decreased. The comparison graph of proposed TPC with existing random linear coding (RLC), NCCARQ-MAC and Huffman coding in regards to hop delay is depicted in Figure 5.

Figure 5 shows that the hop delay of our proposed TPC hop delay is 9.72 X 10⁻³seconds which is significantly lesser than the existing RLC, NCCARQ-MAC and Huffman coding methods. The hop delay value of the existing RLC is 0.010 seconds, Huffman coding achieves 0.012 seconds. The NCCARQ-MAC results in the worst hop delay value with 0.012247 seconds. Regarding hop delay, the relays' dynamic nature has affected the networks' stability, especially in the NC scenario where it was difficult to predict the networks' behavior. However, for the TPC, the performance was better than the NCCARQ-MAC.



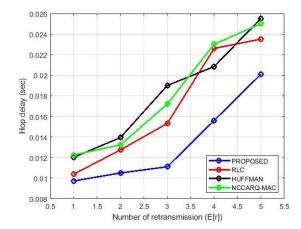


Figure 4. Comparison graph in terms of throughput

Figure 5. Comparison graph in terms of hop delay

4.3. Block error rate

Block Error Rate is characterized as the fraction between numbers of errors packets to the total number of packets transmitted at a certain time. The block error rate is denoted as,

$$E_{block} = \frac{N_{error}}{N_{total}} \tag{14}$$

Where, E_{block} is the block error rate, N_{error} is the number of packets has errors, N_{total} is the total quantity of packets transferred at a specific time. The comparison graph of proposed TPC with existing random linear coding (RLC), NCCARQ-MAC and Huffman coding in regards of block error rate is depicted in Figure 6.

Figure 6 exhibits that the block error rate of our proposed TPC is significantly lower than the existing RLC, NCCARQ-MAC and Huffman coding techniques. The block error rate of the proposed TPC is 0.10, and existing RLC is 0.15, Huffman coding is 0.16. The existing NCCARQ-MAC results in worst block error rate value with 0.20.

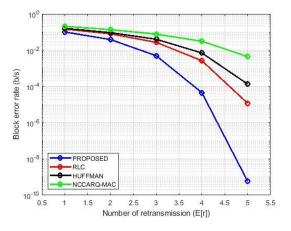
4.4. Packet delivery ratio

This is the ratio of data packets received at the destinations to those transmitted from the source. Mathematically, it is denoted as:

$$\overline{PDR} = \frac{\sum P_{received}}{\sum P_{generated}}$$
 (15)

Where, \overline{PDR} =packet delivery ratio, $\sum P_{received}$ =sum of data packets gotten by every each destination, and $\sum P_{generated}$ =sum of data packets created by every source. The comparison graph of proposed TPC with existing random linear coding (RLC), NCCARQ-MAC and Huffman coding regarding of packet delivery ratio is depicted in Figure 7.

Figure 7 shows that the packet delivery ratio of our proposed TPC is significantly better than the existing RLC, NCCARQ-MAC and Huffman coding methods. The packet delivery ratio of the proposed TPC is 92.81% and the existing RLC is 90.62%, Huffman coding achieves 88.42%. The worst packet delivery ratio of 87.22% is attained for existing NCCARQ-MAC. The networks' stability during stationary relay results to increased packet delivery ratio by the developed TPC as depicted in Figure 7; however, the mobility and the frequent relay changes lowered the packet delivery ratio in the existing RLC, NCCARQ-MAC and Huffman coding as shown in Figure 7.



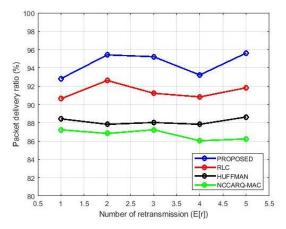


Figure 6. Comparison graph in terms of block error

Figure 7. Comparison graph in terms of packet delivery ratio

4.5. Network decoder outage probability

Consider the direct transmission of the source message (\vec{X}_t) to the destination. When the prompt limit of the channel over which the message is transferred becomes less than the desired rate $D_r(bit/sec/Hz)$, then the destination incorrectly decodes the transferred message, and an outage is said to happen. Let \vec{X}_t be the representation of \vec{X}_t when it is in outage. The outage probability is represented as:

$$P(\tilde{X}_t) = P(\gamma_{s,d} < 2^{\tilde{R}} - 1) \tag{16}$$

$$=1-exp\left(-\frac{2^{\tilde{R}}-1}{\Gamma_{s,d}}\right) \tag{17}$$

Where, $\Gamma_{s,d}$ =transmission path average SNR measured, \bar{R} =exchanged replaced by $2^{\bar{R}}$ in repetition and AQLG network coding-based protocols, and by \bar{R} in phases one and two respectively of coded cooperation protocol because of the shorter time available per phase. The comparison graph of proposed TPC with existing random linear coding (RLC), NCCARQ-MAC and Huffman coding in terms of network decoder outage probability is shown in Figure 8.

Figure 8 shows that the network decoder outage probability of our proposed TPC is significantly higher than the existing RLC, NCCARQ-MAC and Huffman coding techniques. The outage probability value of the proposed TPC is 0.81, and the existing RLC outage probability is 0.975, Huffman coding outage probability is 0.987. Here, the existing NCCARQ-MAC provides the worst packet delivery ratio value with 1 and the proposed TPC provides the best packet delivery ratio value is 0.81.

4.6. Latency

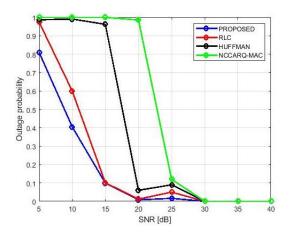
Latency is the time data packet takes to reach the destination. The formula utilized for calculating latency is given in (18).

$$L_{y} = \frac{\sum (T_{arrive} - T_{send})}{\sum N_{linknodes}}$$
 (18)

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Where, L_y =latency, T_{arrive} =arrival time, T_{send} =sending time, $N_{linknodes}$ =number of link nodes. The comparison graph of proposed TPC with existing random linear coding (RLC), NCCARQ-MAC and Huffman coding in terms of latency is shown in Figure 9.

Figure 9 exhibits that the latency of our proposed TPC is significantly lesser than the existing RLC, NCCARQ-MAC and Huffman coding techniques. The latency value of the proposed TPC is 9.72×10^{-3} , existing NCCARQ-MAC is 1.52×10^{-6} and Huffman coding is 1.59×10^{-6} . Here, the existing RLC provides the worst latency with 1.45×10^{-6} seconds and the proposed TPC provides the best latency with 9.72×10^{-3} seconds.



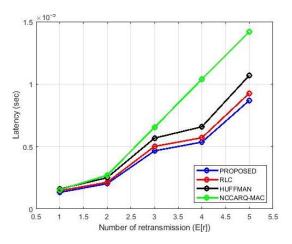


Figure 8. Comparison graph in terms of outage probability

Figure 9. Comparison graph in terms of latency

5. CONCLUSION

This paper presented a transmit packet coding with the cuckoo search-based optimized relay nodes in VANETs. The presented coding technique supports the effective encoding of data packets from specific information flows to improve network performance. This work provides significant insights in support of the proposed TPC-based routing protocols in VANET. In the proposed technique, at first, nodes in the VANET are chosen using the trust- based cuckoo search optimization for secure data transmission. Moreover, the TPC secures the data in the transmission. The experimental outcomes showed that our proposed technique outperformed the existing techniques in terms of performance measures such as network delay, packet delivery ratio, block error rate, outage probability, latency, and throughput. In future work, improved optimization technique can be used for the effective relay selection, as well as develop the improved network coding.

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